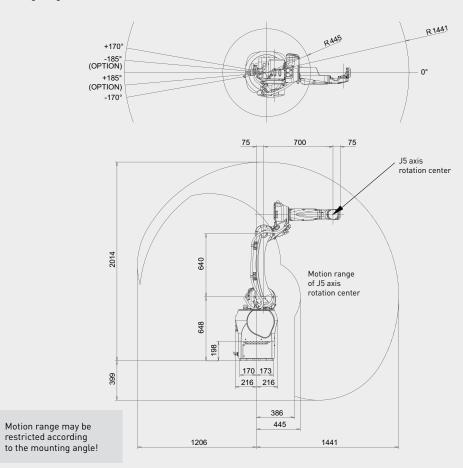
CR-15 <i>i</i> A (Hollow wrist)									Max. load capacity at wrist: <b>15 kg</b> Max. reach: <b>1441 mm</b>			
Controlled axes	Repeatability (mm)	Mechanical weight (kg)	J1	J2	Motion r J3	range (°) J4	J5	J6	Maximum speed (mm/s)	J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
6	± 0.02*	255	340	180	305	380	280	900	800 / 1500* <sup>2</sup>	26.0/0.90	26.0/0.90	11.0/0.30

## Working range



	CR-15 <i>i</i> A
Robot footprint [mm]	346 x 346
Mounting position Floor	•
Mounting position Upside down	•
Mounting position Wall *3	•
Controller	R-30 <i>i</i> B Plus
Open air cabinet	-
Mate cabinet	-
A-cabinet	•
B-cabinet	-
iPendant Touch	•
Electrical connections	
Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1
Integrated services	
Integrated signals on upper arm In/Out	7/5
Integrated air supply	1
Environment	
Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45
Protection	
Body standard/optional	IP54
Wrist & J3 arm standard/optional	IP67

\*1) In case of short distance motion, the speed may not reach the maximum value stated. \*2) if the area is monitored by a safety sensor (located separately)

\*3) In case of the wall mount, the operation space will be restricted according with the payload.